

# Finite element simulations of the bending of an IPMC sheet

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# Background

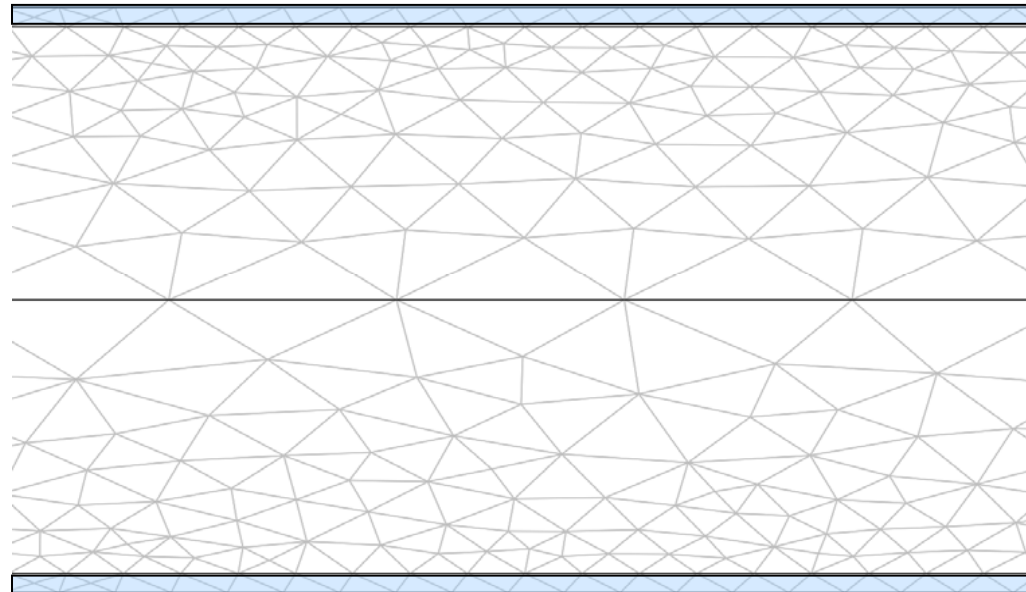


- IPMC – ionic polymer-metal composites are highly porous polymer materials, such as Nafion, filled with some kind of ionic conductive liquid.
- The sheet of polymer material is coated with a thin metal layer – usually platinum or gold.
- In electric field, freely movable ions inside the polymer migrate towards an electrode, causing expansion of material at the one end and contraction at the other end.
- FEM – Finite Element Method
  - Used as a technic of modeling in this work

# Introduction



- The goal: a time dependent FEM model for an IPMC
- The designed model is 2D
- Domains to be considered:
  - Mechanical
  - Electrostatic
  - Mass transfer
- Adding more complexity – electrochemical reactions



# Simulations – cation migration

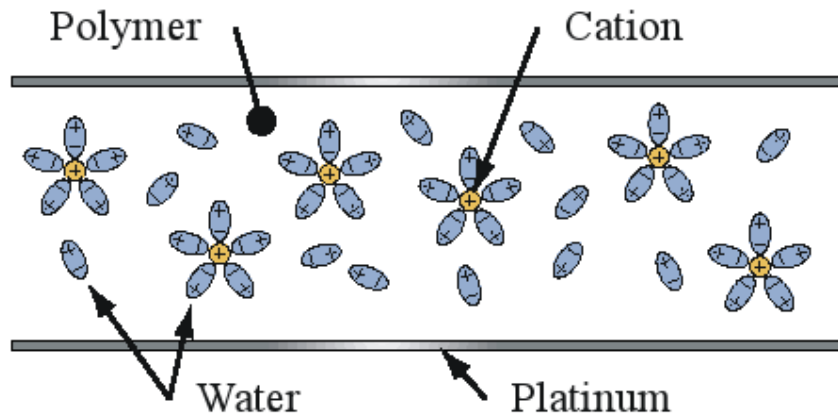


- Nernst-Planck equation:

- Diffusion
- Migration
- Convection

$$\frac{\partial C_i}{\partial t} + \nabla \cdot (-D_i \nabla C_i - z_i \mu_i C_i \nabla \phi) = -\vec{u}_i \cdot \nabla C_i$$

- Voltage causes migration of cations towards cathode
  - That's also the cause of the current in the circuit
- All anions are fixed to the polymer backbone



# Simulations – cation migration (2)

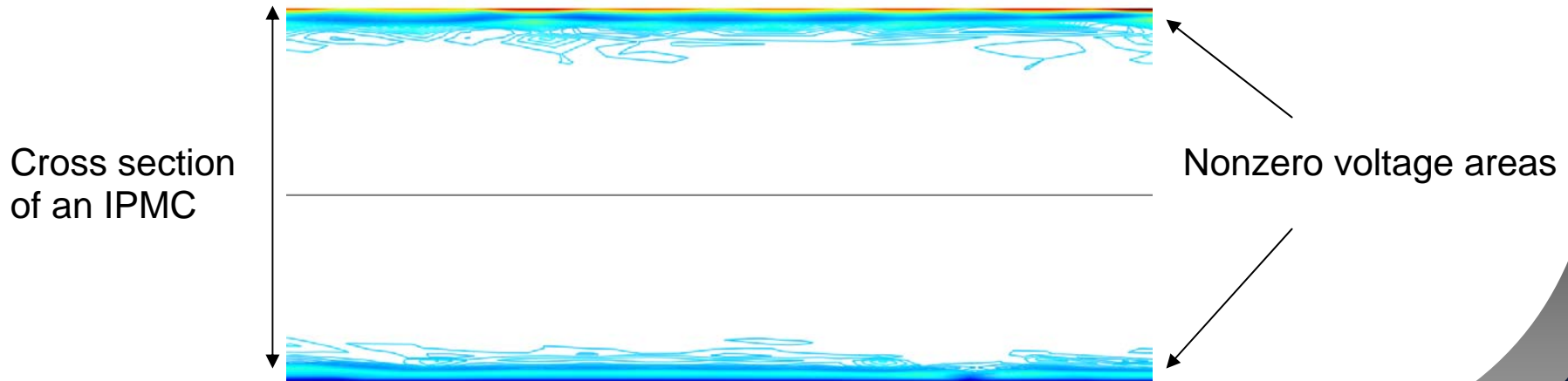


- Charge imbalance inside the IPMC results in electric field
  - opposite to the applied field

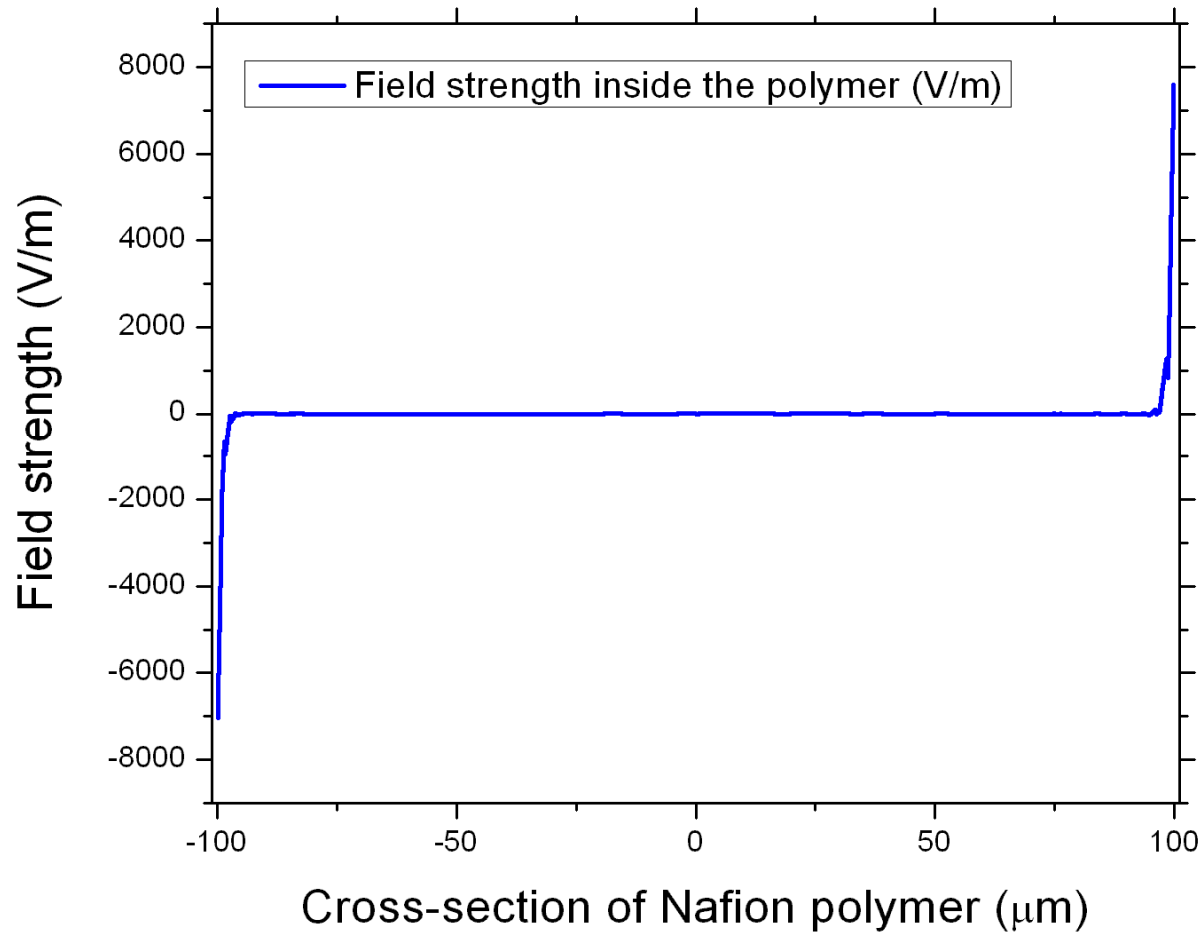
- Gauss' law:

$$\nabla \vec{E} = \frac{F \cdot \rho}{\varepsilon}$$

- Steady state of cations – when the generated field cancels out applied field.



# Simulations – cation migration (3)



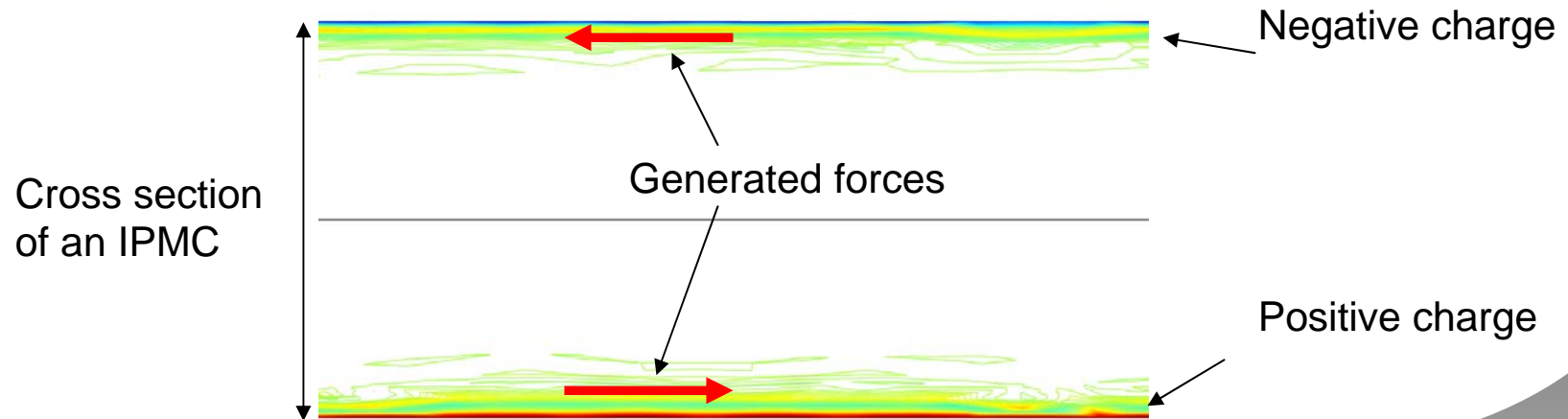
# Actuation of an IPMC



- FEM model – a bit different approach
  - Euler beam model is not used
  - Our model is dynamic, not static
  - Viscoelasticity is also considered
- Assumption – charge imbalance creates longitudinal force inside the IPMC

$$\vec{F} = (A \cdot \rho + \text{sgn}(\rho) \cdot B \cdot \rho^2) \cdot \hat{x}$$

- We consider two terms – charge density and square of the charge density
- Constants A and B are fitted using experimental results



# Mathematics behind the bending



- Continuum mechanics equations are used in the model
- The stress is related to the force in each point of the polymer:

$$-\nabla \cdot \sigma = \vec{F}$$

- The stress is related to strain:

$$\sigma = D\varepsilon$$

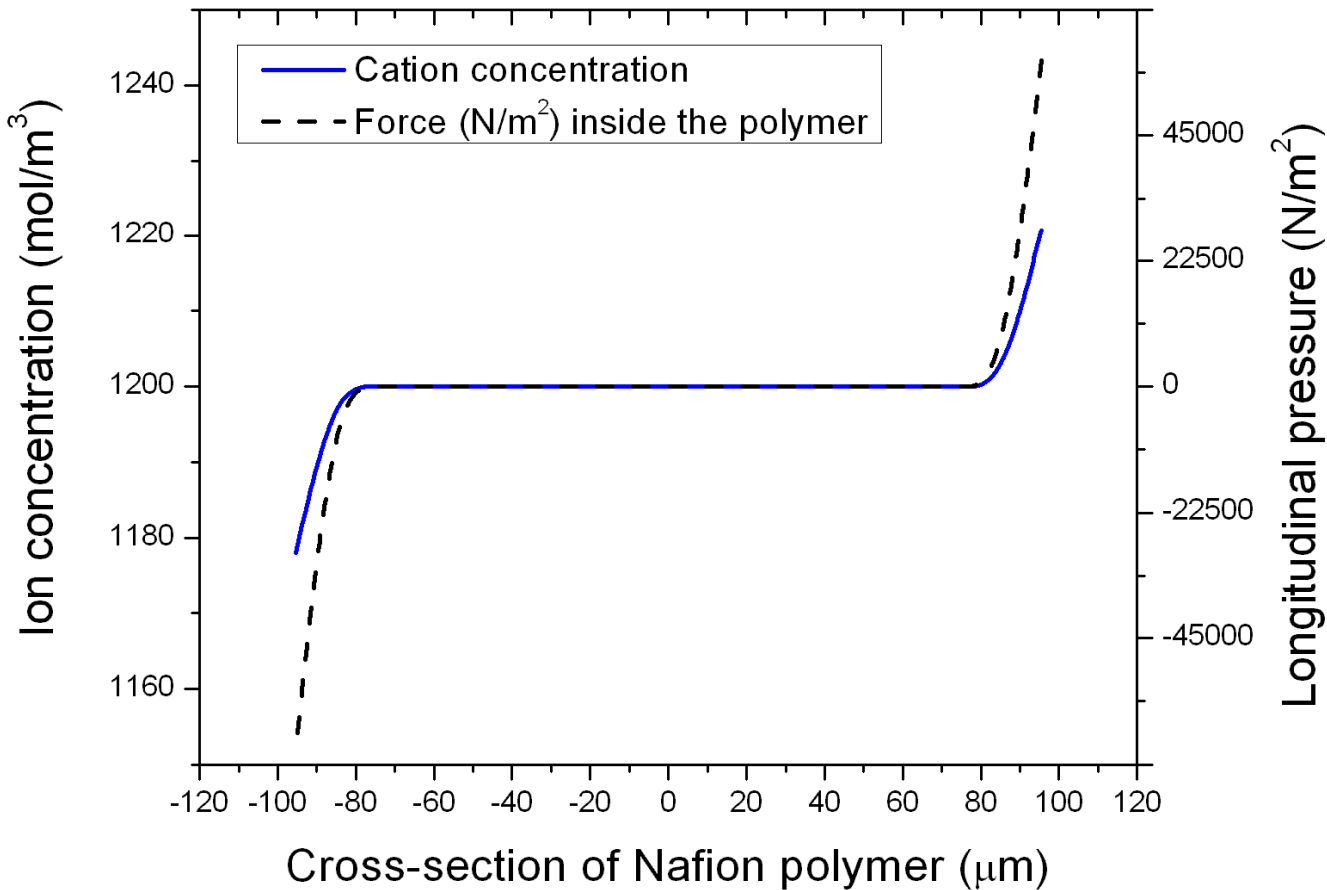
where  $\varepsilon$  and  $\sigma$  are column vectors with dimensions of 6

- Finally, the strain is related to displacement:

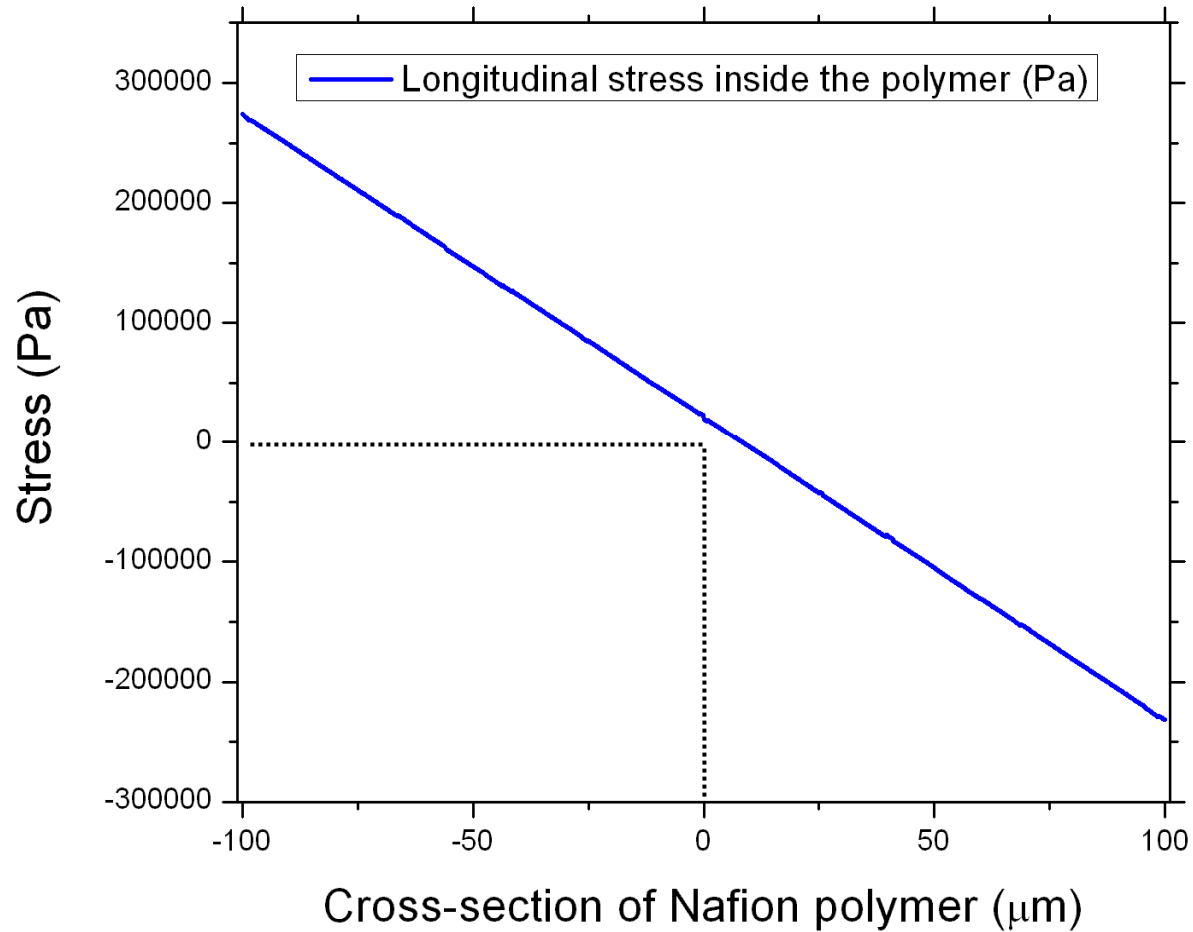
$$\varepsilon_i = \frac{\partial u_i}{\partial x_i}, \varepsilon_{ij} = \frac{1}{2} \left( \frac{\partial u_i}{\partial x_j} - \frac{\partial u_j}{\partial x_i} \right)$$



# Simulations – cation migration, force



# Simulations – generated stress



# Transient analysis of bending



- Time dependent equations  $\rightarrow$  dynamic problem
- Motion of an IPMC sheet is described by:

$$\rho \frac{\partial^2 \vec{u}}{\partial t^2} - \nabla \cdot c \nabla \vec{u} = \vec{F}$$

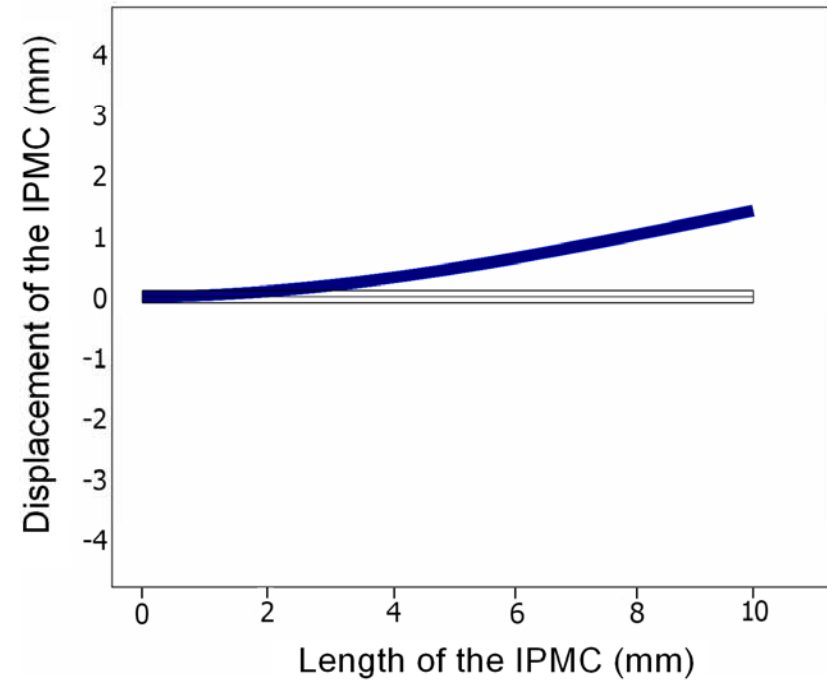
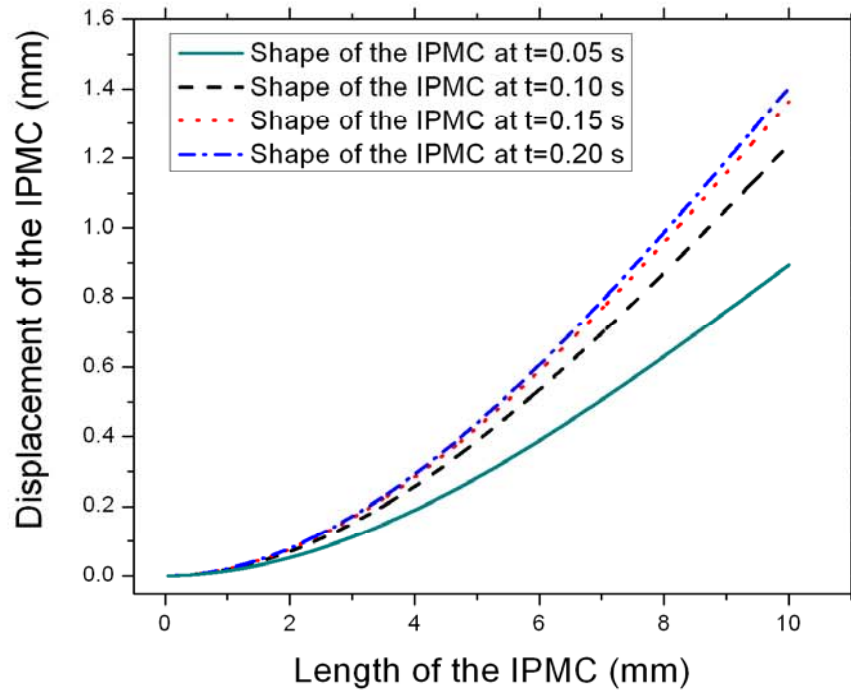
- Rayleigh damping model:

$$m \frac{d^2 u}{dt^2} + \xi \frac{du}{dt} + ku = f(t) \quad \xi = \alpha m + \beta k$$

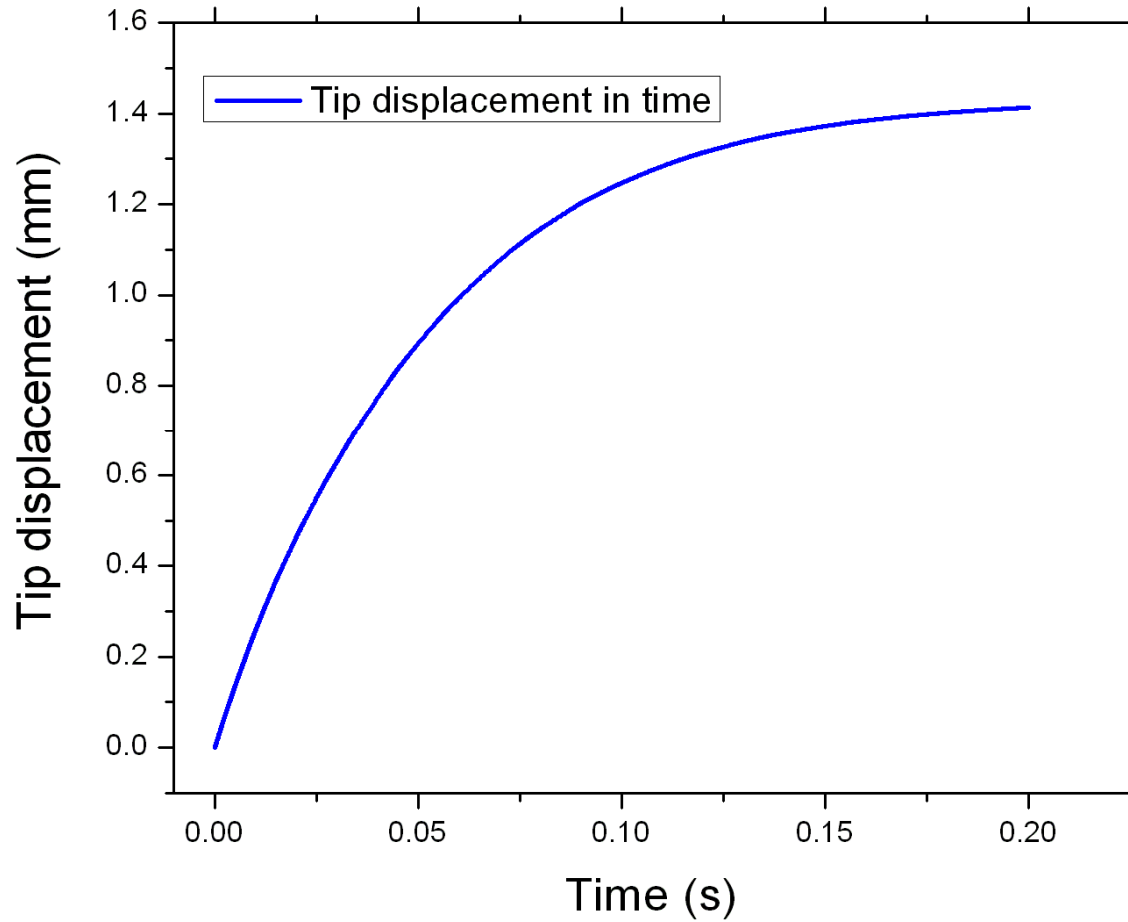
- $\xi$  is a damping parameter.  $m$  is a mass and  $k$  a is stiffness. By coupling those equations for the system of multiple degrees of freedom:

$$\rho \frac{\partial^2 \vec{u}}{\partial t^2} - \nabla \cdot \left[ c \nabla \vec{u} + c \beta \nabla \frac{\partial \vec{u}}{\partial t} \right] + \alpha \rho \frac{\partial \vec{u}}{\partial t} = \vec{F}$$

# Simulation results



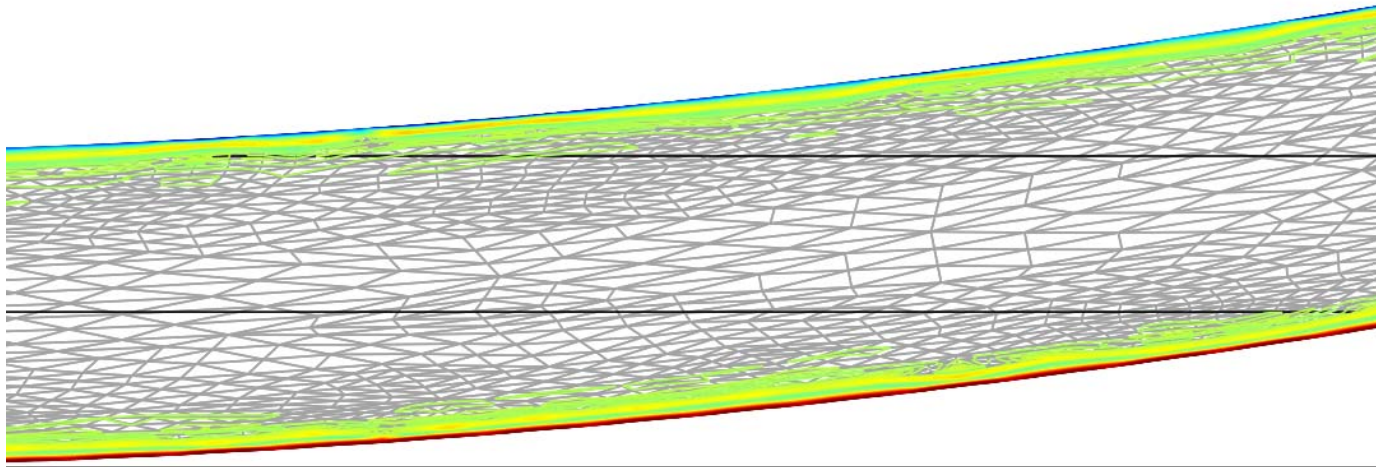
# Tip displacement in time



# Conclusions



- We have a finite element model, which...
  - describes the movement of ions inside the polymer
  - describes the electric field
  - describes the dynamic bending of an IPMC sheet

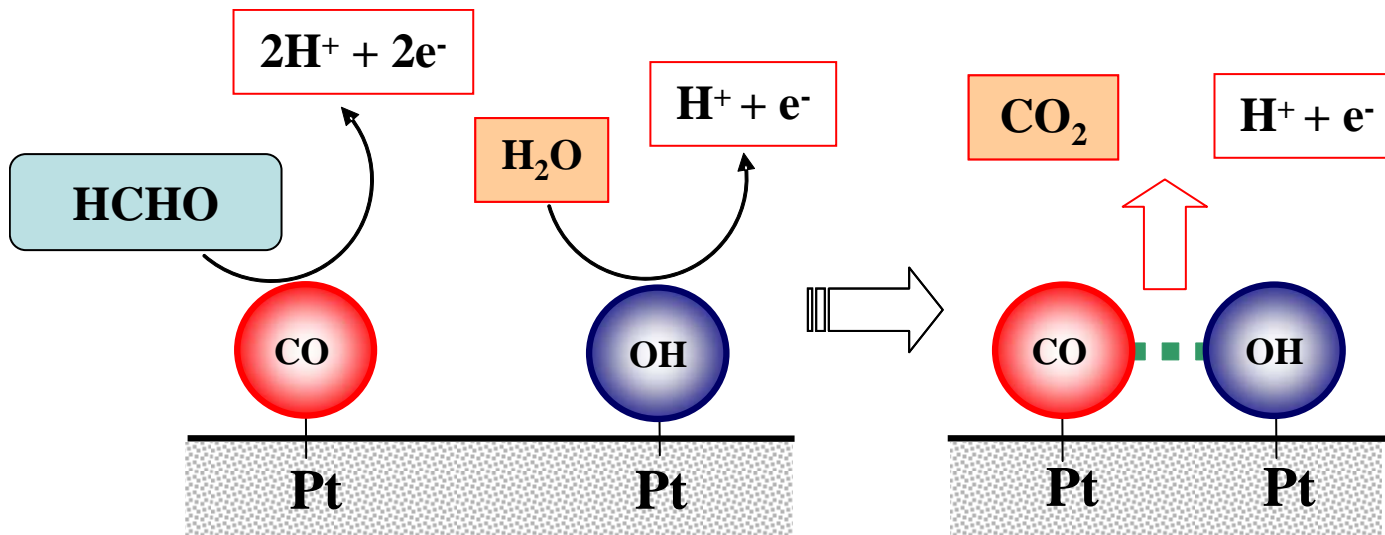


- For next, we add some complexity – electrochemical oscillations

# Self-oscillations



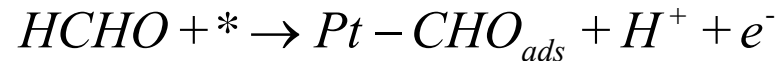
- Electrochemical oscillations – common phenomena in nature
- Oscillations have also been experimentally studied
- Tests with IPMC:
  - immersed into acidic formaldehyde (HCHO) solution
  - applied constant voltage  $\sim 0.75V$
  - result: current oscillations and oscillating bending
- Cause of the oscillations are electrochemical reactions on the Pt surface



# Simulating self-oscillations



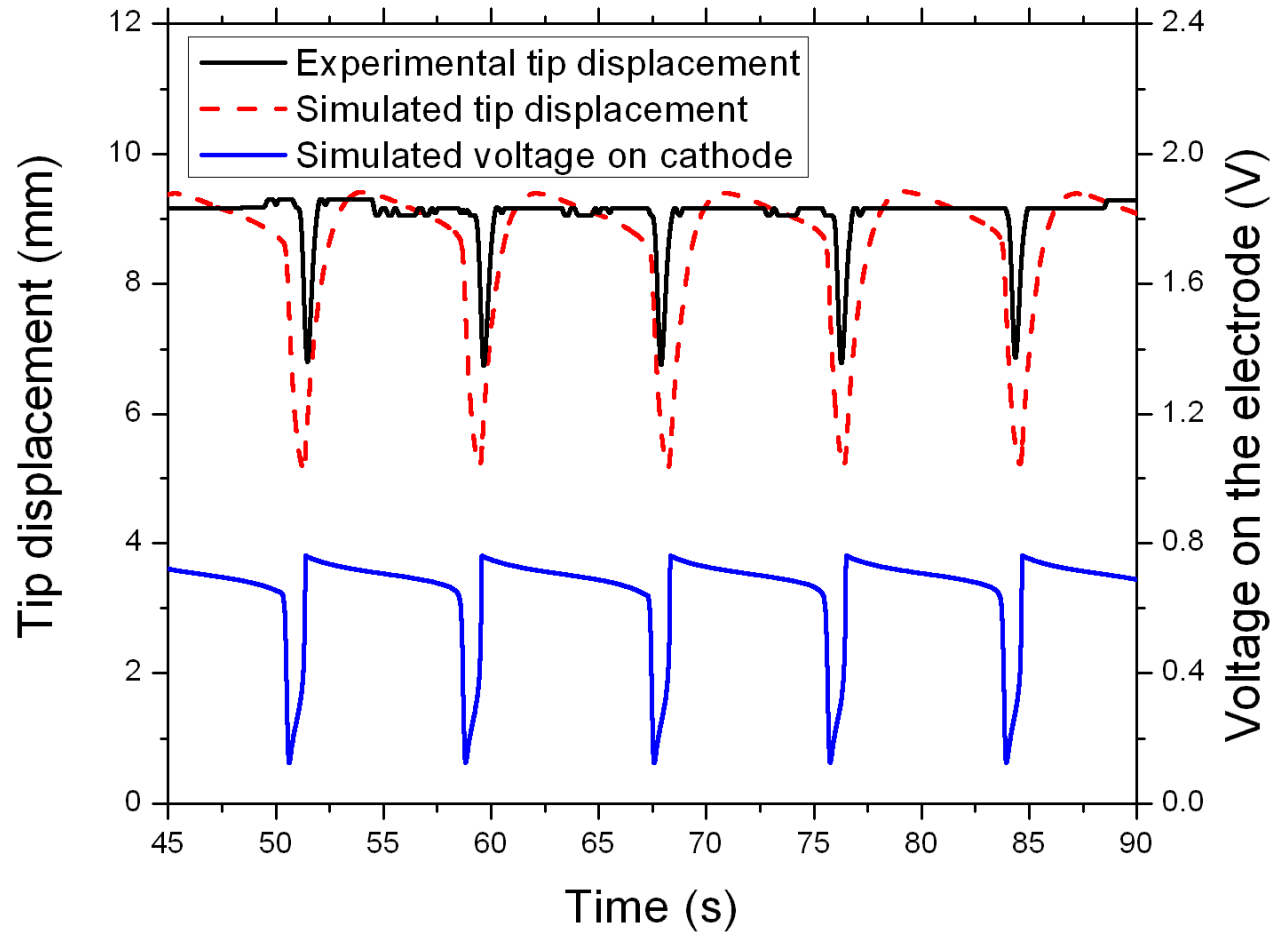
- A double layer were initialized near the platinum surface.
- On that surface, the following reaction is modeled:



- 4 dynamic variables must be modeled on the platinum surface
  - time dependence of adsorption coverage of CO
  - time dependence of adsorption coverage of OH
  - HCHO concentration change in double layer
  - time dependence of potential on cathode
- These equations were coupled to the basic model...



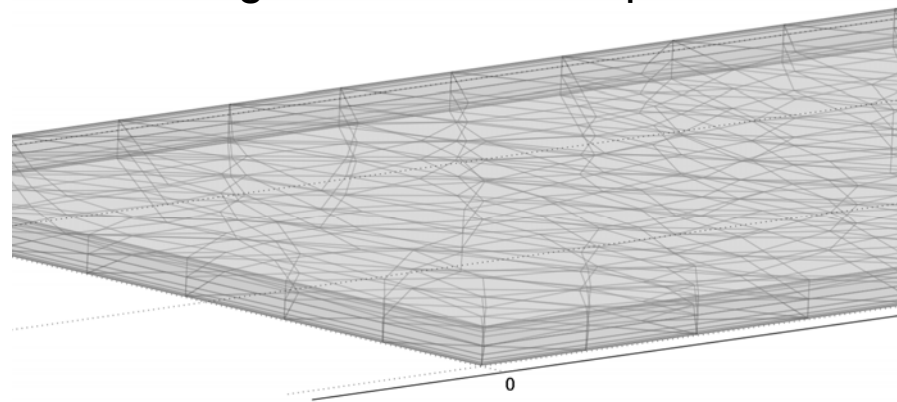
# Self-oscillations – model and experiment



# Conclusions and future plans



- 2D, basic FEM model was developed to describe time dependent actuation of an IPMC muscle
- In addition, more complexity was added by coupling a problem of electrochemistry – self oscillatory actuation
- Also experimental and simulation results were compared and quite good agreement were found
- For future:
  - Adding 3<sup>rd</sup> dimension to the model
  - Considering fluid viscosity and corresponding equations inside the polymer
  - Work on the simulating the oscillation equations



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# Questions



Thank you for your attention!