## Propagators for the Time Dependent Kohn-Sham Equations



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TDKS propagators

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#### Theoretical Framework

• Kohn-Sham Equations

$$\epsilon_i |\phi_i\rangle = \hat{H}_{[n]} |\phi_i\rangle$$

 $n(\mathbf{r}) = \sum_{i} \psi_{i}^{\dagger}(\mathbf{r})\psi_{i}(\mathbf{r})$ 

• Time-dependent Kohn-Sham Equations

$$i\hbar \frac{\mathrm{d}}{\mathrm{d}t} |\phi_i\rangle = \hat{H}(t)_{[n(t)]} |\phi_i\rangle$$
$$i\hbar \frac{\mathrm{d}}{\mathrm{d}t} |\phi_i\rangle = \left\{ \hat{T} + \hat{V}^{\mathsf{external}}(t) + \hat{V}^{\mathsf{HXC}}_{[n(t)]} \right\} |\phi_i\rangle$$
$$\stackrel{\mathsf{T}}{\to} -\frac{\nabla^2}{2m}$$
$$\stackrel{\mathsf{Vext}}{\to} (t) \to \text{ ion potential} + \mathbf{E}(t) \cdot \mathbf{r} \text{ (for example)}$$
$$\stackrel{\mathsf{VHXC}}{\to} \int \frac{n(\mathbf{r}', t)}{|\mathbf{r} - \mathbf{r}'|} d\mathbf{r}' + V^{\mathsf{XC}}[n(t)](\mathbf{r}) \text{ (Adiabatic LDA)}$$

#### Similar Problems

Time Dependent Kohn-Sham equations (TDKS)

$$\mathrm{i}\hbar rac{\mathrm{d}}{\mathrm{d}t} |\phi_i\rangle = \hat{H}(t)_{[n(t)]} |\phi_i\rangle$$

Time Dependent Schrödinger Equation (TDSE)

$$\mathrm{i}\hbarrac{\mathrm{d}}{\mathrm{d}t}|\phi
angle=\hat{H}(t)|\phi_i
angle$$

Non-linear Schrödinger Equation (NLSE)

$$i\partial_t \psi = -\frac{1}{2}\partial_x^2 \psi + \kappa |\psi|^2 \psi$$

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#### Numerical Integration

Concerns

Accuracy,

e.g. method is order  $\mathcal{O}(\Delta t)^4$ 

Stability,

e.g. numerical error increases as  $exp(\gamma(\Delta t)T)$ 

• "Physical" properties,

e.g. method conserves energy or norm exactly

#### Euler Method A First Method

# • Derivation $$\begin{split} &\mathrm{i}\hbar\frac{\mathrm{d}}{\mathrm{d}t}|\phi_i\rangle = \hat{H}|\phi_i\rangle \\ &\mathrm{i}\hbar\frac{|\phi_i(t+\Delta t)\rangle - |\phi_i(t)\rangle}{\Delta t} + \mathcal{O}(\Delta t)^2 = \hat{H}|\phi_i(t)\rangle \\ &|\phi_i(t+\Delta t)\rangle = |\phi_i(t)\rangle - \frac{\mathrm{i}}{\hbar}\Delta t\hat{H}|\phi_i(t)\rangle + \mathcal{O}_{\mathsf{local}}(\Delta t)^2 \end{split}$$

• Integration Error (order)

$$ightarrow |\phi_i(t)
angle + \mathcal{O}_{ ext{integration}}(\Delta t)$$

Not Stable!

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#### Second Order Differences (SOD), Part I

Second order in time

$$|\phi_i(t + \Delta t)\rangle = |\phi(t - \Delta t)\rangle - 2\mathrm{i}\Delta t \hat{H}[n(t)]|\phi_i(t)\rangle$$

• Integration Error (order)

$$ightarrow |\phi_i(t)
angle + \mathcal{O}_{ ext{integration}}(\Delta t)^2$$

- Conditionally Stable of TDSE
- Unconditionally Unstable for TDKS

Criterion of Stability from Local Analysis

$$\frac{\partial u}{\partial t} = \alpha \frac{\partial^2 u}{\partial x^2}$$

• Discretization (finite differences) in time and space

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• Discretization (finite differences) in time and space

• Eigenmode analysis 
$$u_j^n \to \xi(k)^n e^{ikj\Delta x}$$
  
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Criterion of Stability from Local Analysis

$$\frac{\partial u}{\partial t} = \alpha \frac{\partial^2 u}{\partial x^2}$$

• Discretization (finite differences) in time and space

$$\underbrace{u_{j}^{n}}_{\text{res}} \underbrace{u_{j}^{n+1} - u_{j}^{n}}_{\text{res}} = \alpha \frac{\left(u_{j+1}^{n} - 2u_{j}^{n} + u_{j-1}^{n}\right)}{\Delta t}$$

• Eigenmode analysis  $u_j^n o \xi(k)^n e^{\mathrm{i} k j \Delta x}$ 

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$$\xi(k) = 1 - 4 \frac{|\alpha| \Delta t}{\Delta x^2} \sin^2(k \Delta x/2)$$

• Stability Criterion  $|\xi| \leq 1$ 

Criterion of Stability from Local Analysis

$$\frac{\partial u}{\partial t} = \alpha \frac{\partial^2 u}{\partial x^2}$$

Discretization (finite differences) in time and space

$$\underbrace{\underbrace{u_{j}^{n+1} - u_{j}^{n}}_{x \neq j} \xrightarrow{\text{FTCS}} \frac{u_{j}^{n+1} - u_{j}^{n}}{\Delta t} = \alpha \frac{\left(u_{j+1}^{n} - 2u_{j}^{n} + u_{j-1}^{n}\right)}{\Delta x^{2}}$$

• Eigenmode analysis  $u_i^n \rightarrow \xi(k)^n e^{ikj\Delta x}$ 

•

$$\xi(k) = 1 - 4 \frac{|\alpha|\Delta t}{\Delta x^2} \sin^2(k\Delta x/2)$$

• Stability Criterion  $|\xi| \leq 1$ 

$$\frac{2|\alpha|\Delta t}{\Delta x^2} \leq 1 \longrightarrow \frac{\Delta t \times E_{\text{cutoff}}^{\text{PW}}}{\pi^2 \hbar \, \text{mode}} \leq 1$$

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#### Second Order Differences (SOD) for TDSE, Part II



Analysis valid only for TDSE

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### Stabilizing SOD

The effect of the self consistent potential



Updating the Hamiltonian once every several steps help stabilize the integration

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#### Runge-Kutta 4th Order

A conditionally stable, accurate method



#### Parallel Scalability



No orthogonalization bottleneck !



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#### Cayley's Method (Crank Nicholson) An Implicit Method

$$\left\{ \hat{1} + \frac{1}{2} i \hat{\mathcal{H}}[n(t + \Delta t)] \Delta t \right\} |\psi_i(t + \Delta t)\rangle = \left\{ \hat{1} - \frac{1}{2} i \hat{\mathcal{H}}[n(t)] \Delta t \right\} |\psi_i(t)\rangle$$
(1)

Future step is an implicit function of the previous step (need a non linear solution).

An approximation (use past density)

$$\left\{\hat{1}+\frac{1}{2}\hat{H}[n(t)]\Delta t\right\}|\psi_{i}(t+\Delta t)\rangle = \left\{\hat{1}-\frac{1}{2}\hat{H}[n(t)]\Delta t\right\}|\psi_{i}(t)\rangle \quad (2)$$

Still not very suitable for PW expansion.

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- TDKS Propagators are subject to stability issues (like any PDE)
- Methods that work for TDSE may not work at all for TDKS
- RK4 presents good accuracy and stabiliry (at least for  $T = 100 \mathrm{fs}$ )
- Plane-wave accuracy
- Parallel efficiecy up to 1500 cores for 450 electrons

References: Schleife et al., "Explicit integrators for the time-dependent Kohn-Sham equations within the plane-wave pseudopotential formalism",